## **Multi-Resolution Techniques**

### Sung-Eui Yoon (윤성의)

#### Course URL: http://jupiter.kaist.ac.kr/~sungeui/SGA/



# At the Previous Class

#### • The overview of the course

Culling techniques



## Problems

#### Even after visibility culling we can still have too many visible triangles





372 million triangles (10GB)

**13M Triangles** 



# Problems

- Won't this problem go away with faster GPUs?
  - The real world has virtually infinite complexity
  - Our ability to model and capture this complexity can outpace rendering performance



# Multi-Resolution or Levels of Detail

#### Basic idea

 Render with fewer triangles when model is farther from viewer



Viewer

- Polygonal simplification
- Parametric and subdivision surfaces
- Image impostors



Lower

resolution

# **Polygonal Simplification**

 Method for reducing the polygon count of mesh



- Two main components
  - Simplification operators
  - Simplification error metrics



# **Simplification Operators**

- Vertex clustering
- Edge collapse
- Vertex removal



# Vertex Clustering [Rossignac & Borrel 93]

- Impose a grid on the model
- Compute weighted average vertex in each cell
- Triangles become:
  - Triangles
  - Lines
  - Points





# **Vertex Clustering**

- Main benefits
  - Simple and robust
- Disadvantages
  - Hard to target a polygon count
  - Poor error control





# Edge Collapse [Hoppe93]



- Fine grained
  - Reduce two triangles at most
- Allows simple geomorphs
- Topology preserving





# **Virtual Edge Collapse**

- Extension of edge collapse to two vertices not connected by an edge
  - Allows topological simplification
  - Usually limited to small distance to avoid O(n<sup>2</sup>) virtual edges





# **Simplification Error Metric**

- Control and quantify the quality of the LOD
  - Ultimately, we want to measure appearance
  - Typically, we use a geometric measure as an approximation
- Error measures are used in three ways
  - To pick which parts are simplified
  - To determine the simplified mesh from the operation (e.g. position of the new vertex)
  - To choose an LOD at runtime
- Two common LOD selection criteria
  - Target frame rate vs. target quality



# Hausdorff Distance

A measure of surface deviation

- H(A,B)=max(h(a,b),h(b,a)), where h(A,B)=max<sub>a</sub>min<sub>b</sub>(|a-b|)
- h is called the one-sided Hausdorff distance
- Provides a bound on the maximum possible error
  - Project to screen space to get deviation in pixels





# Vertex Plane Distance [Ranford 96]

 One metric is the max distance between the vertex and the planes of the supported triangles





# Quadric Error Metric [Garland & Heckbert 97]

- Use sum of squared distance rather than max distance
  - Can be efficiently computed and empirically shows very good results



Excerpted from [Garland & Heckert 97]



# Attributes

#### Vertices have more than just position:

- Colors
- Normals
- Texture coords
- Shader programs



# **Overall Simplification Process**

- Compute simplification candidates
- While (there is candidate)
  - Pick a candidate with the smallest error
  - Perform the simplification



# **View-Dependent Rendering**

#### Use different resolutions according to view points

• [Clark 76, Funkhouser and Sequin 93]



- Static levels-of-detail (LODs)
- Dynamic (or view-dependent) simplification



# **Static LODs**

#### • Pre-compute discrete simplified meshes

- Switch between them at runtime
- Has very low LOD selection overhead



**Excerpted from Hoppe's slides** 

# **Dynamic Simplification**

- Provides smooth and varying LODs over the mesh [Hoppe 97]
  - 1<sup>st</sup> person's view

3<sup>rd</sup> person's view



Play video



# **Vertex Hierarchy**





# **View-Dependent Refinement**



#### Front representing a LOD mesh



- Representation
- Construction
- Runtime computation
- Integration with other acceleration techniques



- Representation
- Construction

22+GB for 100M triangles [Hoppe 97]

- Runtime computation
- Integration with other acceleration techniques



- Representation
- Construction
- Runtime computation
- Integration with other acceleration techniques



- Representation
- Construction

Rendering throughput of 3M triangles per sec [Lindstrom 03]

- Runtime computation
- Integration with other acceleration techniques



- Representation
- Construction
- Runtime computation



Integration with other acceleration techniques



- Representation
- Construction
- Runtime computation
- Integration with other acceleration techniques



## **Toward Scale-able Dynamic Simplification Method**

- View-dependent rendering [Yoon et al. VIS 04]
  - New multi-resolution hierarchy (CHPM)
  - Out-of-core construction for general meshes
  - Applied to collision detection [Yoon et al. SGP 04] and shadow computation [Lloyd et al. EGSR 06]
- Cache-oblivious layouts [Yoon et al. SIG 05]
  - High GPU utilization during rendering



## Live Demo – View-Dependent Rendering [Yoon et al., SIG 05]



30 Pixels of error

Pentium 4

GeForce Go 6800 Ultra

**1GB RAM** 

#### Double Eagle Tanker 82 Million triangles

![](_page_29_Picture_7.jpeg)

## **Clustered Hierarchy of Progressive Meshes (CHPM)**

- Novel dynamic simplification representation
  - Cluster hierarchy
  - Progressive meshes

![](_page_30_Picture_4.jpeg)

![](_page_30_Picture_5.jpeg)

## **Clustered Hierarchy of Progressive Meshes (CHPM)**

#### Clusters

- Spatially localized regions of the mesh
- Main processing unit for view-dependent computation
- Cluster hierarchy
  - Used for visibility computations and out-ofcore rendering

![](_page_31_Picture_6.jpeg)

![](_page_31_Picture_7.jpeg)

## **Clustered Hierarchy of Progressive Meshes (CHPM)**

- Progressive mesh (PM) [Hoppe 96]
  - Each cluster contains a PM as an LOD representation

![](_page_32_Figure_3.jpeg)

![](_page_32_Picture_4.jpeg)

- Coarse-grained view-dependent refinement
  - Provided by selecting a front in the cluster hierarchy
  - Inter-cluster level refinements

![](_page_33_Picture_4.jpeg)

![](_page_33_Picture_5.jpeg)

- Coarse-grained view-dependent refinement
  - Provided by selecting a front in the cluster hierarchy
  - Inter-cluster level refinements

![](_page_34_Figure_4.jpeg)

![](_page_34_Picture_5.jpeg)

- Coarse-grained view-dependent refinement
  - Provided by selecting a front in the cluster hierarchy
  - Inter-cluster level refinements

![](_page_35_Figure_4.jpeg)

![](_page_35_Picture_5.jpeg)

- Fine-grained local refinement
  - Supported by performing vertex splits in PMs
  - Intra-cluster refinements
    - Efficient and effective representation for massive models!

![](_page_36_Figure_5.jpeg)

![](_page_36_Picture_6.jpeg)

# **Main Properties of CHPM**

- Low refinement cost
  - 1 or 2 order of magnitude lower than previous representations
- Alleviates visual popping artifacts
  - Provides smooth transition between different LODs

![](_page_37_Picture_5.jpeg)

![](_page_38_Figure_1.jpeg)

![](_page_39_Figure_1.jpeg)

![](_page_40_Figure_1.jpeg)

![](_page_41_Figure_1.jpeg)

## **Out-of-Core Hierarchical Simplification**

#### Simplifies clusters bottom-up

![](_page_42_Figure_2.jpeg)

## **Out-of-Core Hierarchical Simplification**

#### Simplifies clusters bottom-up

![](_page_43_Figure_2.jpeg)

# **Boundary Simplification**

![](_page_44_Figure_1.jpeg)

# **Boundary Simplification**

![](_page_45_Figure_1.jpeg)

# **Boundary Constraints**

- Common problem in many hierarchical simplification algorithms
  - [Hoppe 98; Prince 00; Govindaraju et al. 03]

![](_page_46_Picture_3.jpeg)

# **Boundary Constraints**

![](_page_47_Picture_1.jpeg)

![](_page_47_Picture_2.jpeg)

# **Boundary Constraints**

![](_page_48_Figure_1.jpeg)

![](_page_48_Picture_2.jpeg)

 Replaces preprocessing constraints with runtime dependencies

![](_page_49_Picture_2.jpeg)

![](_page_50_Figure_1.jpeg)

![](_page_51_Figure_1.jpeg)

## **Cluster Dependencies at Runtime**

![](_page_52_Figure_1.jpeg)

![](_page_52_Picture_2.jpeg)

# **Chained Dependency**

#### Inappropriate for refinements

![](_page_53_Figure_2.jpeg)

![](_page_53_Picture_3.jpeg)

![](_page_54_Figure_1.jpeg)

![](_page_54_Picture_2.jpeg)

![](_page_55_Figure_1.jpeg)

# **Runtime Performance**

Model	Pixels-
Power plant	1
Iso- surface	10
St. Matthew	1

Model	Pixels-of- errors	Frame rate	Model size
Power plant	1	28	1GB
Iso- surface	10	18	2.5GB
St. Matthew	1	29	13GB

![](_page_56_Picture_3.jpeg)

# **Other Forms of LOD**

- Image impostors
- Shader LOD
  - Number of shaders
  - Number of textures
- Simulation LOD
  - Time steps
  - Simulation resolution
  - Number of particles
- Lighting
  - Number and type of lights used

![](_page_57_Picture_11.jpeg)

# Next Time..

#### Study cache-coherent algorithms

![](_page_58_Picture_2.jpeg)