Team 2 Project Presentation

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6 December 2023

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Overview

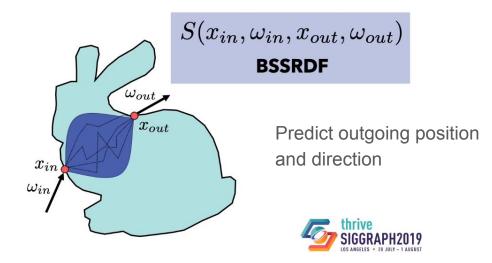
- 1. A Learned Shape-Adaptive Subsurface Scattering Model (SIGGRAPH 2019)
 - a. Review
 - b. Improving idea
 - c. Failure
- 2. Flexible SVBRDF Capture with a Multi-Image Deep Network (EGSR 2019)
 - a. Brief introduction
 - b. Limitation
 - c. Improving idea & Failure
- 3. Conclusion
- 4. Role Division

First Try:

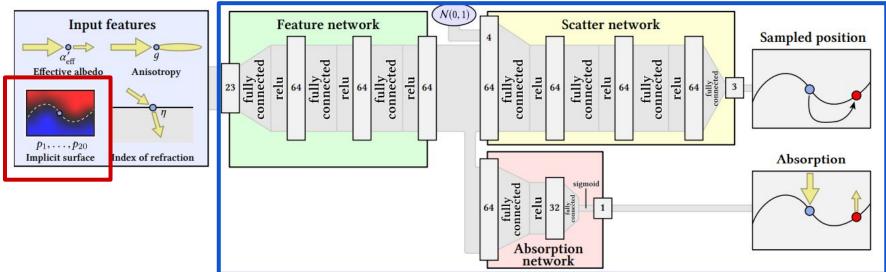
A Learned Shape-Adaptive Subsurface Scattering Model

by D. Vicini, V. Koltun, W. Jakob, SIGGRAPH 2019

- Methods for implementing subsurface scattering
- Inefficient method (sampling RTE) vs unrealistic method (BSSRDF)
- => Kill two birds rabbits with one stone using **Neural Network**

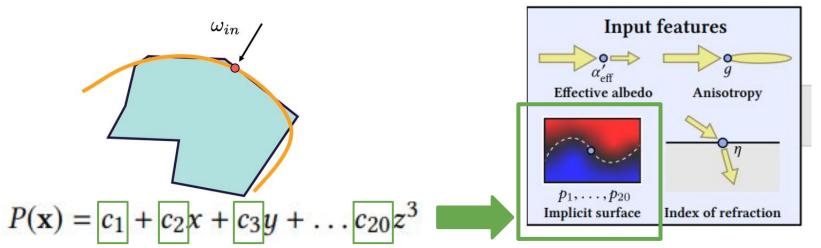


- They use **neural networks** to extract features, outgoing location, and absorption information
- However, for obtaining **geometric information**, they employ **polynomials** instead of neural networks



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- Approximate **polynomial** -> **Coefficients** of polynomial as **input**

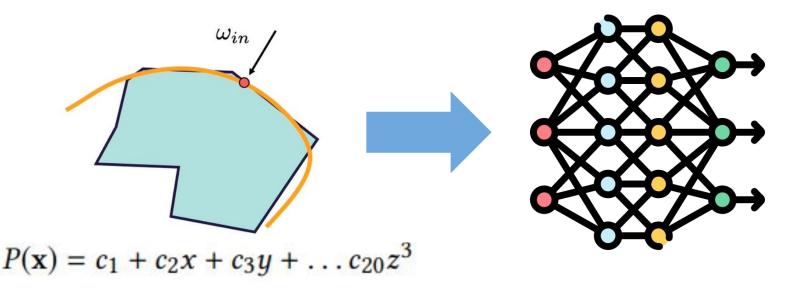


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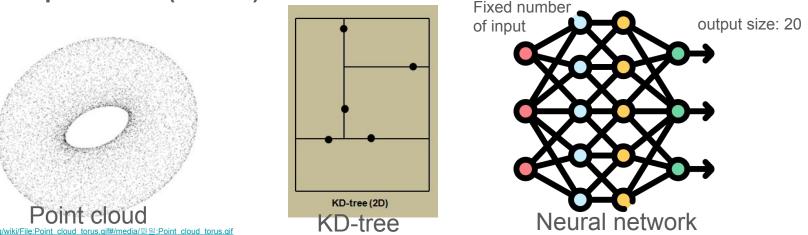


We may consider **replacing** the **polynomial** with a **neural network**.

- Key idea: Replace **polynomial** with **neural network**
- The network is jointly trained with other networks(feature, scatter, absorption)
- If successful with **simple one**, we planned to explore **more complex one**



- Input in code: **KD-tree** data structure generated from **point clouds** obtained through 3D scanning objects
- Polynomial: KD-tree -> polynomial fitted => its coefficients (20)
- Neural Network: KD-tree -> a fixed number of random points from the tree
 - => output vector (dim:20)

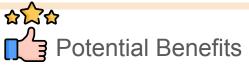




- Improved prediction quality; able to learn diverse data representations
- Method simplicity

Fotential Drawbacks

- Lower prediction quality
- Decrease in speed
- Risk of overfitting



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 - Lower prediction quality
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[Requirements]

Mitsuba renderer 0.6

Python 2.7.x

Scons 2.x

Visual Studio 2010

```
@misc{Mitsuba,
Author = {Wenzel Jakob},
Year = {2010},
Note = {http://www.mitsuba-renderer.org},
Title = {Mitsuba renderer}
}
```

Challenges in **downloading** due to outdated versions

Errors arose from the installation of a slightly newer version

Compiling Mitsuba's dependencies on Windows is a laborious process; for convenience, there is a repository that provides them in precompiled form. To use this repository, clone it using Mercurial and rename the directory so that it forms the dependencies subdirectory inside the main Mitsuba directory, i.e. run something like

C:\>cd mitsuba C:\mitsuba\>hg clone https://www.mitsuba-renderer.org/hg/dependencies_windows C:\mitsuba\>rename dependencies_windows dependencies

There are a few other things that need to be set up: make sure that your installation of Visual Studio is up to date, since Mitsuba binaries created with versions prior to Service Pack 1 will crash. Next, you will need to install Python 2.7.x (www.python.org) and SCons⁴ (http://www.scons. org, any 2.x version will do) and ensure that they are contained in the %PATH% environment variable so that entering scons on the command prompt (cmd.exe) launches the build system.

⁴Note that on some Windows machines, the SCons installer generates a warning about not finding Python in the registry. In this case, you can instead run python setup.py install within the source release of SCons.

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Service Temporarily Unavailable

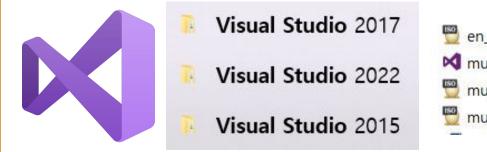
The server is temporarily unable to service your request due to maintenance downtime or capacity problems. Please try again later.

Apache/2.2.22 (Debian) Server at www.mitsuba-renderer.org Port 443

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 mu_microsoft_build_tools_2013_x86_300...
 mu_visual_studio_2010_sp1_x86_dvd_651...
 mu_visual_studio_2013_update_3_x86_dv...

	Release version	Release date
	Python 2.6.7	June 3, 2011
	Python 2.5.6	May 26, 2011
	Python 3.2.0	Feb. 20, 2011
	Python 2.7.1	Nov. 27, 2010

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⁴Note that on some Windows machines, the SCons installer generates a warning about not finding Python in the registry. In this case, you can instead run python setup.py install within the source release of SCons.

- Numerous errors occurred without clear reasons.
- Despite substantial efforts, we encountered difficulties in building the Mitsuba 0.6 renderer

	itsuba>scons
	l Python error: Py_Initialize: unable to load the file system codec
Requirement already satisfied: mitsuba in c:\user	leNotFoundError: No module named 'encodings'
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ModuleNotFoundError	
D:\mitsuba>scons -V	· · · · · · · · · · · · · · · · · · ·
D:\ProgramFiles\python3.10\Scripts\scons.py:99: Deprecation	nWarning: p\KAIST\ICG\mitsuba\SConstruct", line 12, in <module></module>
pkg_resources is deprecated as an API. See	sers\Lavinia\Desktop\KAIST\ICG\mitsuba\config.py"
https://setuptools.pypa.io/en/latest/pkg_resources.html	.3 not installed. C/C++ compilers are most likely not set correctly.
import pkg_resources	p\KAIST\ICG\mitsuba\build\SConscript.configure", line 96, in <module></module>
SCons import failed. Unable to find engine files in:	17

Email to TA

Can we get some **advice** about how to **build Mitsuba0.6**? Is it problem of version?

> I don't have experience working with Mitsuba0.6, where my work is based on the recent Mitsuba3

Also, python 2.7 is very **outdated**

Ask to Classmates

Does anyone know how to **build Mitsuba0.6**?

I tried to build it, but it's very **difficult**. We now do **another project without Mitsuba**.

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Reason for Failure: Huge & complex code

- Huge & complex project with difficult code
 - files and functions utilized across different files
- High probability of **failing to revise** the code **correctly** even if the build was successful

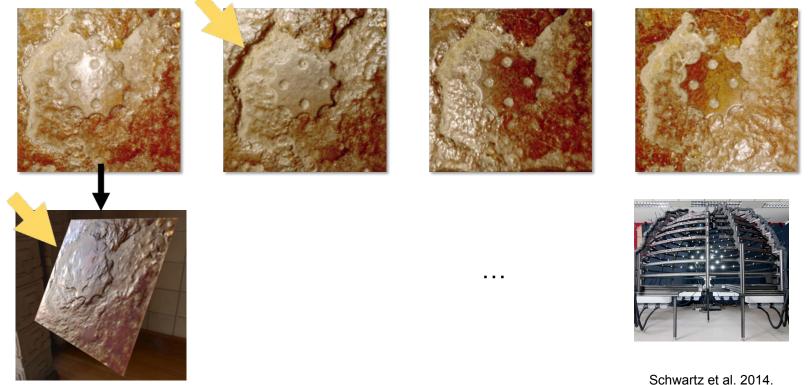
Files	learned-subsurface-scattering / src /	Add file 🔹 ····
₽ master + Q	g dvicini learned bssrdf: missing header files, fix build errors	aaf1382 · 4 years ago 🕚 History
Q Go to file		
🗋 render.cpp	Name	Last commit date
> 📄 librender	· · ·	
> 🖿 medium	bsdfs	6 years ago
> 📄 mitsuba	Converter	6 years ago
> 📄 mtsgui	emitters	б years ago
> 🖿 phase	films	6 years ago
> in rfilters	10015	o years ago
> 📄 samplers	integrators	4 years ago
> in sensors	🖿 libbidir	6 years ago
> 📄 shapes		
🗸 🧰 subsurface	libcore	4 years ago
🗅 SConscript	🖿 libhw	5 years ago

Second Try:

Flexible SVBRDF Capture with a Multi-Image Deep Network

by Valentin Deschaintre, Miika Aittala, Fredo Durand, George Drettakis and Adrien Bousseau, EGSR 2019

Brief Introduction of the Paper



Li et al. 17, Deschaintre et al. 18, Li et al. 18

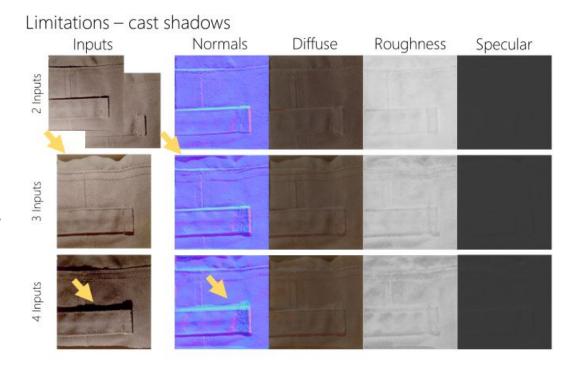
Schwartz et al. 2014. University of Bonn's Dome

Limitations Mentioned in the Paper

Use **normal maps** to represent orientation variations

-> Cannot render cast shadows and parallax

-> The **network** doesn't really **know** how to **represent these effects**

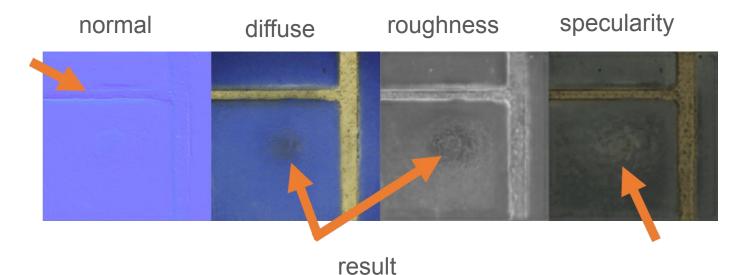


Limitations Mentioned in the Paper

- One image may not be enough

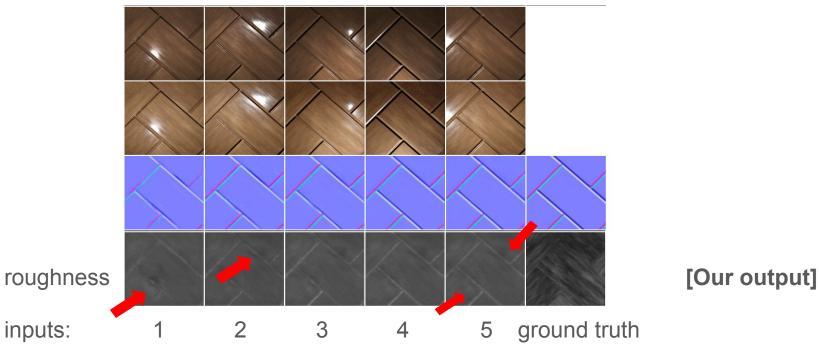


input



Limitation we found

- Using a **flash** -> **artifacts** as visible in diffuse and **roughness**
- Problem remains even for 5 input images (not only for 1 image)



- Key idea: more (higher resolution) training data
- Failure: training process got eliminated, newly trained weights* produce
 wrong images on same test data, but we don't know why



*dataset from:

https://team.inria.fr/graphdeco/

Conclusion: Learn from Failure

First Try:

- If implementation fails first few times, don't waste time and move on
- Evaluate the difficulty of optimization before choosing a thesis
- Conceptualizing improvement is still possible by analysing paper and code
- Ensure that the code environment used is relatively new and easy to operate

Second Try:

- Mostly failed due to time constraints
- Idea can still be used for future work

Role Division

• Janu Kim

- Analysis of both papers
- Understanding core concepts

• Yiwen Mao

- Old paper code compilation
- Analysis of new paper

• Tamana Pirzad

- New paper code compilation
- Finding solution to new paper

Thank You :) 감사합니다! 谢谢! Bedankt!