

Reparameterizing Discontinuous Integrands for Differentiable Rendering, SIGGRAPH Asia 2019

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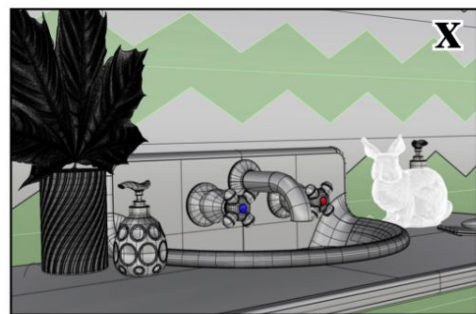
Agenda

1. Differentiable Rendering
2. Review of Edge Sampling
3. Reparametrizing Integrals
4. Results

Differentiable Rendering

- Allows the gradients of 3D objects to be calculated and propagated through images
- Crucial to optimization, inverse problem, and deep learning
- Gradient w.r.t camera parameters, light sources, scene geometry, material appearance

Differentiable Rendering



Input parameters
shape & position of objects, materials,
light sources, camera pose, etc.

Differentiable
physical simulation

$$\mathbf{y} = f(\mathbf{x})$$

$$\frac{\partial \mathbf{y}}{\partial \mathbf{x}} = \frac{\partial}{\partial \mathbf{x}} f(\mathbf{x})$$



Output
rendered image

Differentiable
objective function

$$z = g(\mathbf{y})$$

$$\frac{\partial z}{\partial \mathbf{y}} = \frac{\partial}{\partial \mathbf{y}} g(\mathbf{y})$$

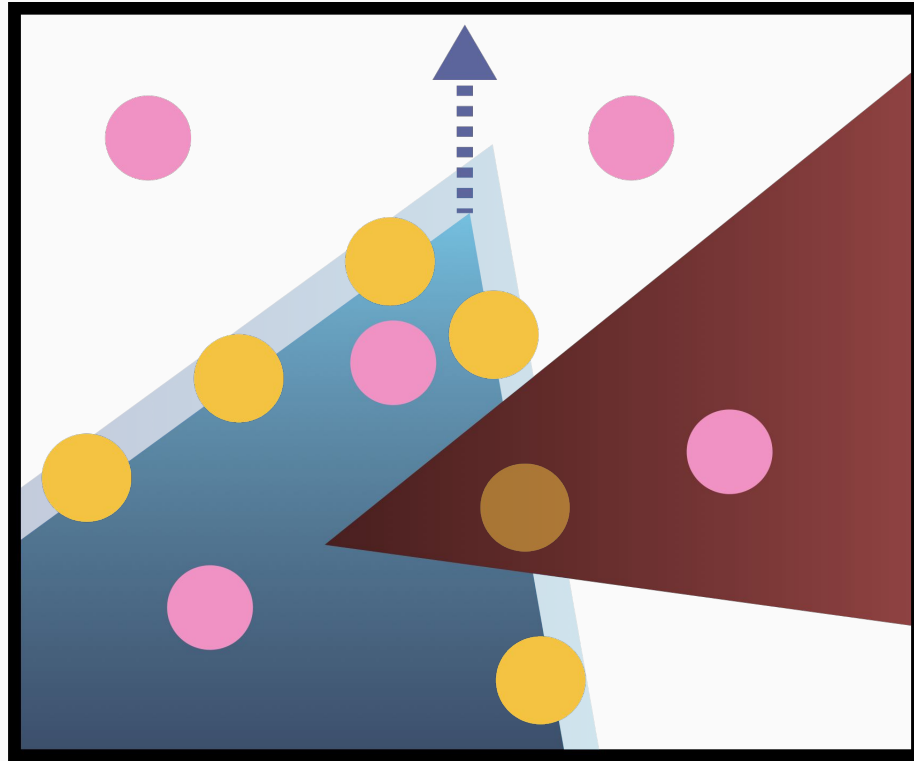
$z \in \mathbb{R}$

$\frac{\partial z}{\partial \mathbf{x}}$

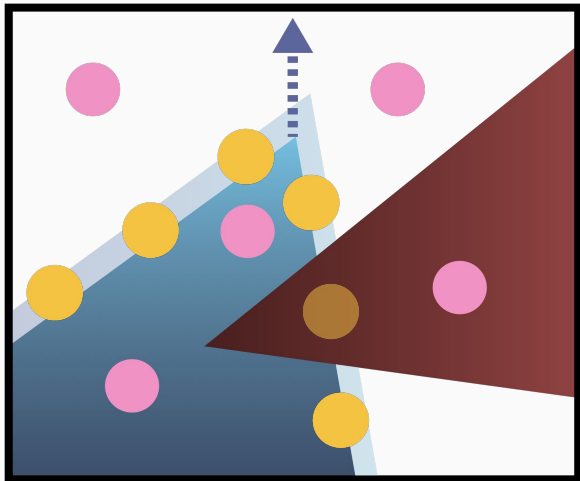
Update scene

Zhao, Shuang, Wenzel Jakob, and Tzu-Mao Li. "Physics-based differentiable rendering: from theory to implementation." ACM SIGGRAPH 2020 Courses. 2020. 1-30.

Review of Edge Sampling



Review of Edge Sampling



- Model edge using step function
- Differentiation
- Monte Carlo Sampling
- Edge sampling \rightarrow bottleneck

$$\nabla \int \int \theta(\alpha_i(x, y)) f_i(x, y) dx dy$$

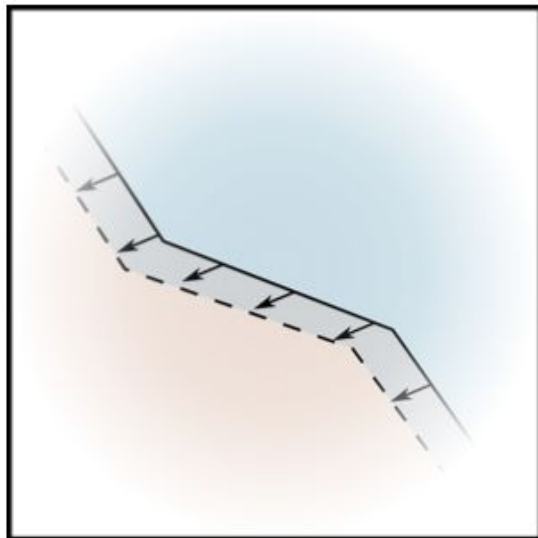
$$= \int \int \delta(\alpha_i(x, y)) \nabla \alpha_i(x, y) f_i(x, y) dx dy$$

$$+ \int \int \theta(\alpha_i(x, y)) \nabla f_i(x, y) dx dy$$

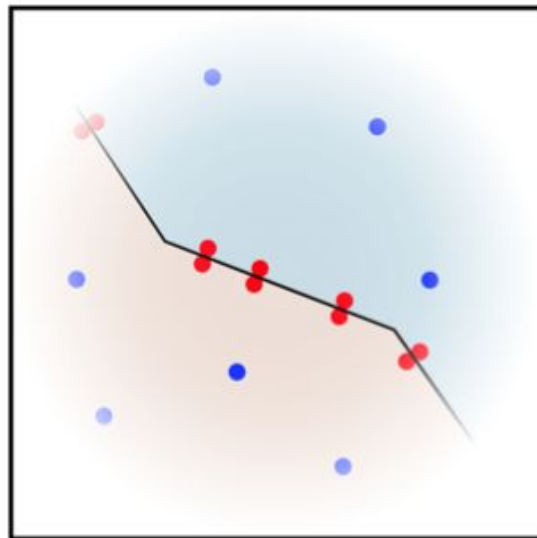
Goal:

Compute gradient
without edge sampling

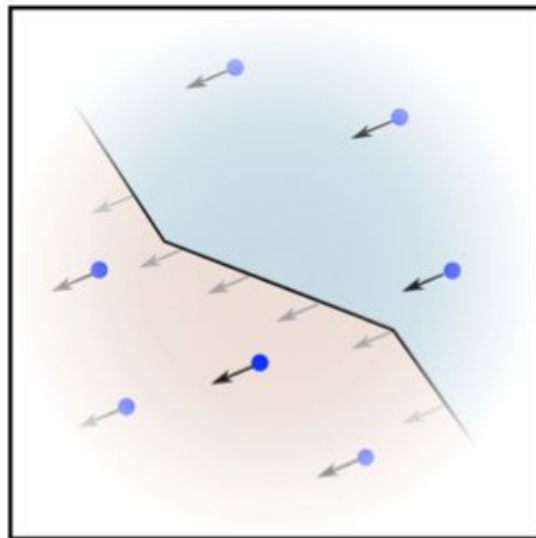
Reparametrizing Integrals - Example



(a) Integrand with discontinuity



(b) Edge sampling
[Li et al. 2018]



(c) Using changes of variables (ours)

Approach: Reparametrizing Integrals

- Parameter that affects the positions of discontinuities
- Move sample points along the discontinuity
- → Discontinuity becomes static w.r.t the parameter

Reparametrizing Integrals

d : Location of discontinuity

θ : Step function

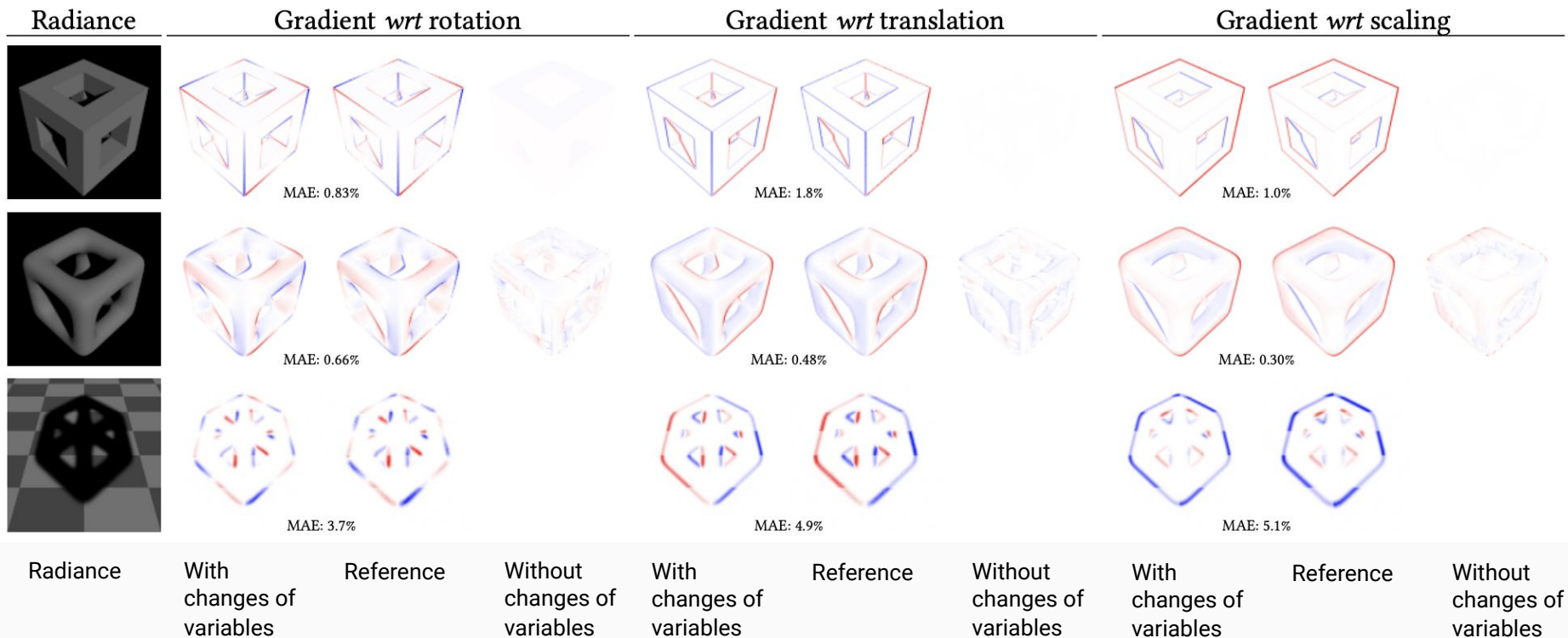
$$\begin{aligned} I &= \int_X \theta(x - d)k(x)dx \\ &= \int_Y \theta(y)k(y + d)dy \end{aligned} \quad \begin{array}{l} \curvearrowright \\ y = x - d \end{array}$$

→ No delta function in the derivative w.r.t d

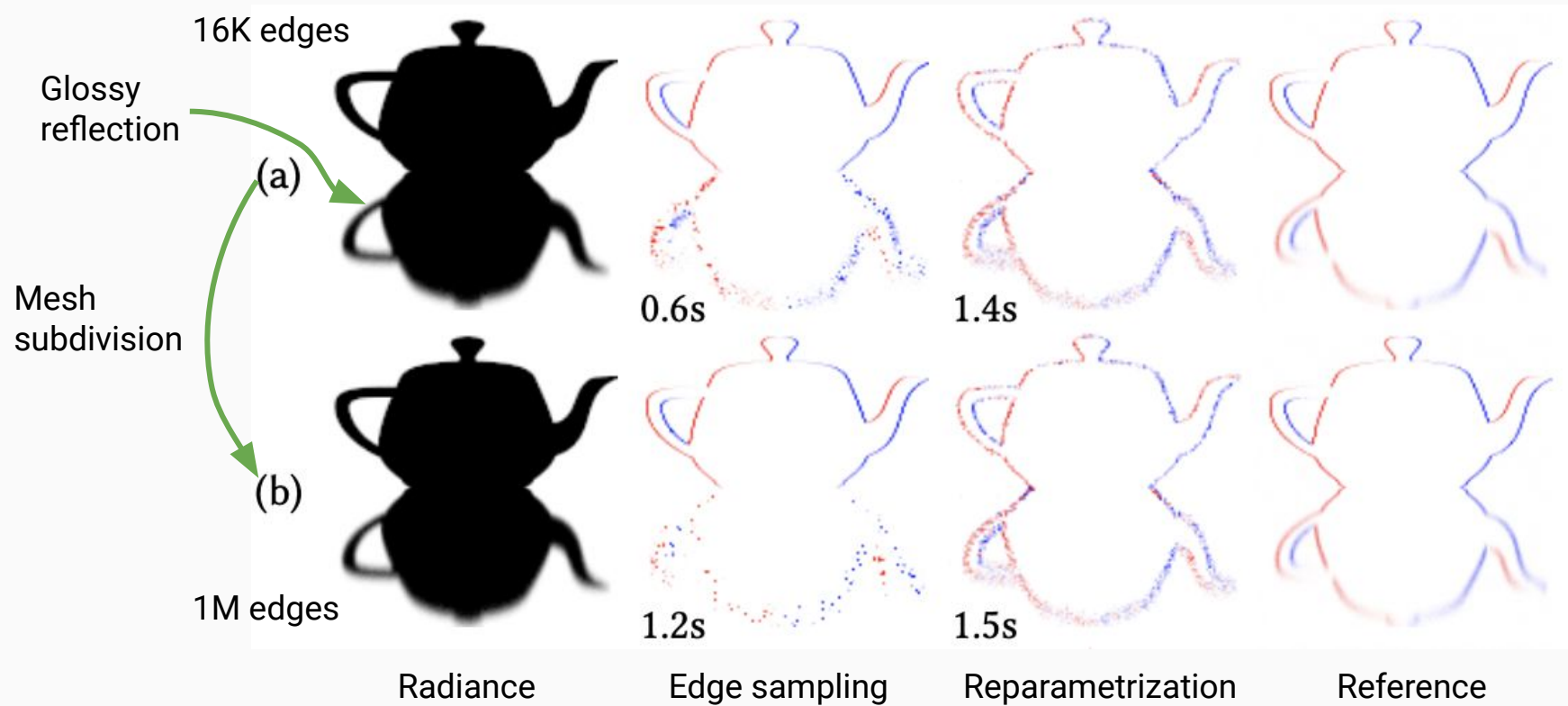
Details

- Assumes only one discontinuity in a pixel
 - Apply convolution to the smooth the integrand
- Change of variables using rotation to eliminate discontinuity
- Variance reduction
 - Control variates using pairs of correlated paths
 - Reuse random numbers to sample correlated paths

Results - vs Reference Gradient



Results - vs Edge Sampling



Results - vs Edge Sampling

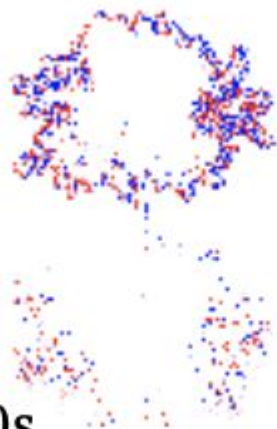
5M edges



Radiance

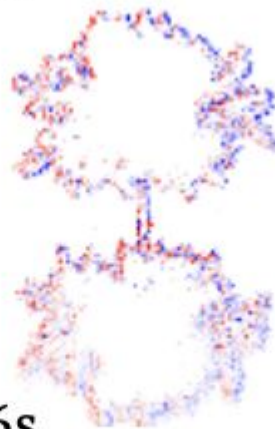
Glossy reflection

3.0s

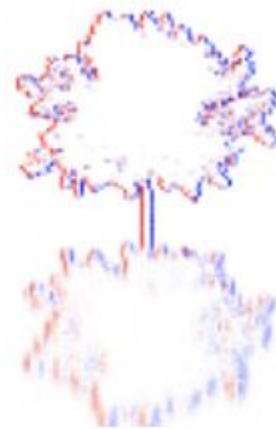


Edge sampling

1.6s



Reparametrization



Reference

Application - Reconstruction from Rendered Image

Multi-view shape and texture optimization using gradient descent

Synthetic example, optimized using 5 views (4 are shown)



Input scene

Target (rendered)



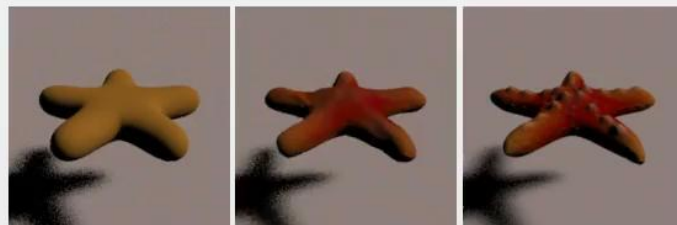
Input scene

Target (rendered)



Input scene

Target (rendered)



Input scene

Target (rendered)

Application - Reconstruction from Photo

Multi-view shape and texture optimization using gradient descent

Optimized using 5 photos (4 are shown)



Input scene

Target (photo)



Input scene

Target (photo)



Input scene

Target (photo)



Input scene

Target (photo)

Summary

- Edge sampling → bottleneck
- Differentiable path tracer without edge sampling
- Reparametrization → Monte Carlo estimators become differentiable
- Scales to scenes with high geometric and depth complexity
- More robust to complex geometry, shadows, and glossy reflections
 - For primary visibility, edge sampling is more robust

Limitations

- Significant variance in cases including high-order diffuse interreflection
 - Variance reduction is less effective for higher number of bounces
- Assumption of single discontinuity in a pixel
 - Two discontinuities in a pixel - explicit edge sampling
 - Did not manifest in optimization problems conducted in this work

Thank you! :)