CS482: Radiosity

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Course URL: http://sglab.kaist.ac.kr/~sungeui/ICG



Class Objective (Ch. 11)

Understand radiosity

- Radiosity equation
- Solving the equation



History

Problems with classic ray tracing

- Not realistic
- View-dependent
- Radiosity (1984)
 - Global illumination in diffuse scenes
- Monte Carlo ray tracing (1986)
 - Global illumination for any environment

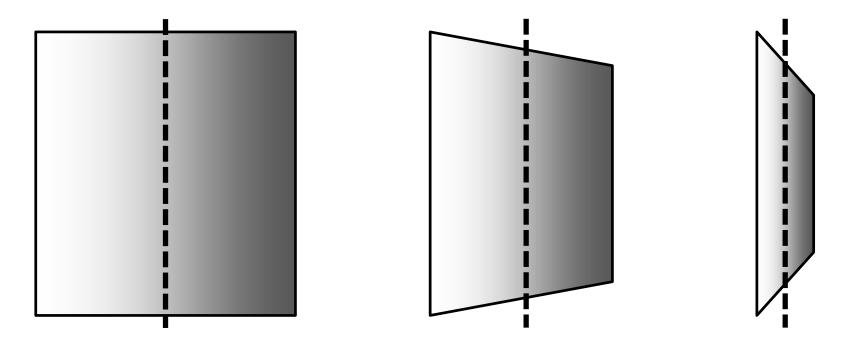


Radiosity

- Physically based method for diffuse environments
 - Support diffuse interactions, color bleeding, indirect lighting and penumbra
 - Account for very high percentage of total energy transfer
 - Finite element method



Key Idea #1: Diffuse Only



Radiance independent of direction

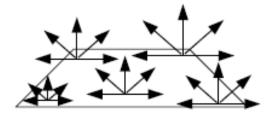
- Surface looks the same from any viewpoint
- No specular reflection



Diffuse Surfaces

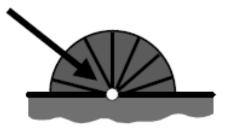
• Diffuse emitter

• $L(x \rightarrow \Theta) = \text{constant over } \Theta$



Diffuse reflector

Constant reflectivity



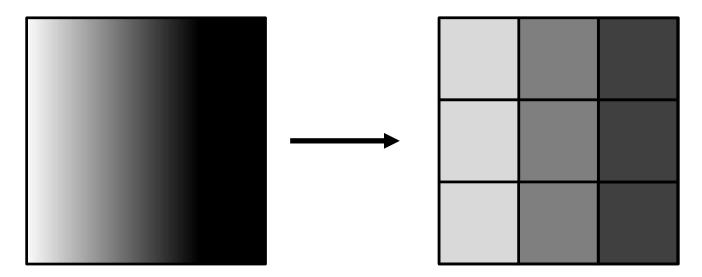
From kavita's slides



Key Idea #2: Constant Polygons

Radiosity is an approximation

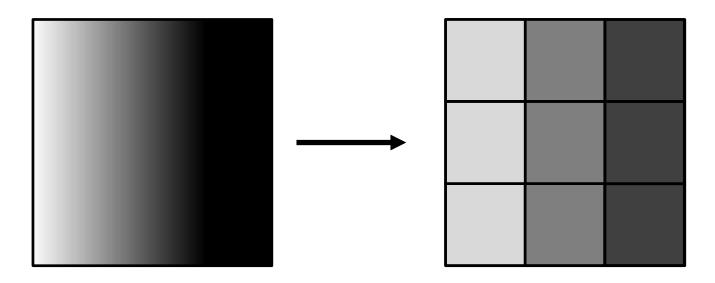
Due to discretization of scene into patches



Subdivide scene into small polygons



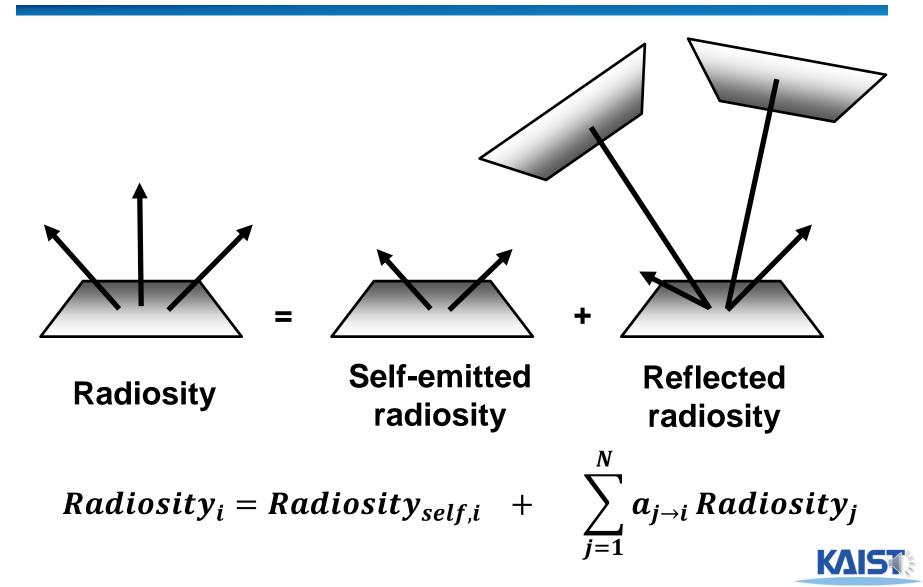
Constant Radiance Approximation



- Radiance is constant over a surface element
 - L(x) = constant over x



Radiosity Equation



Radiosity Equations

• Radiosity for each polygon i

$$\begin{aligned} Radiosity_{1} &= Radiosity_{self,1} + \sum_{j=1}^{N} a_{j \to 1} Radiosity_{j} \\ &\vdots \\ Radiosity_{i} &= Radiosity_{self,i} + \sum_{j=1}^{N} a_{j \to i} Radiosity_{j} \\ &\vdots \\ Radiosity_{N} &= Radiosity_{self,N} + \sum_{j=1}^{N} a_{j \to N} Radiosity_{j} \end{aligned}$$

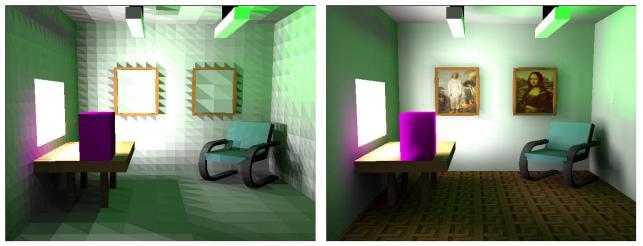
N

N equations and N unknown variables



Radiosity Algorithm

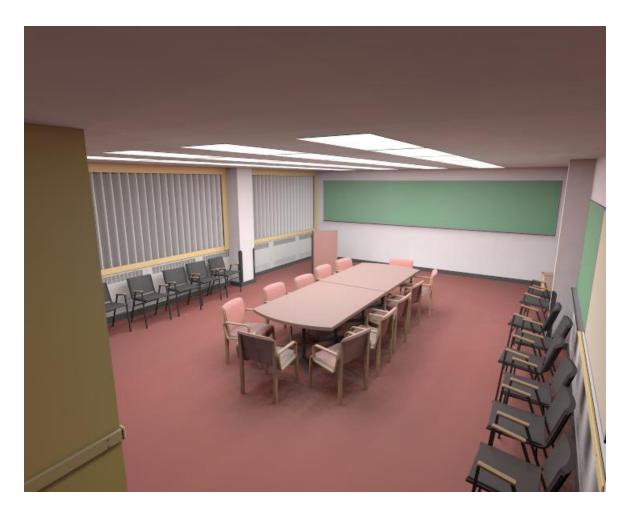
- Subdivide the scene in small polygons
- Compute a constant illumination value for each polygon
- Choose a viewpoint and display the visible polygon
 - Keep doing this process





From Donald Fong's slides

Radiosity Result

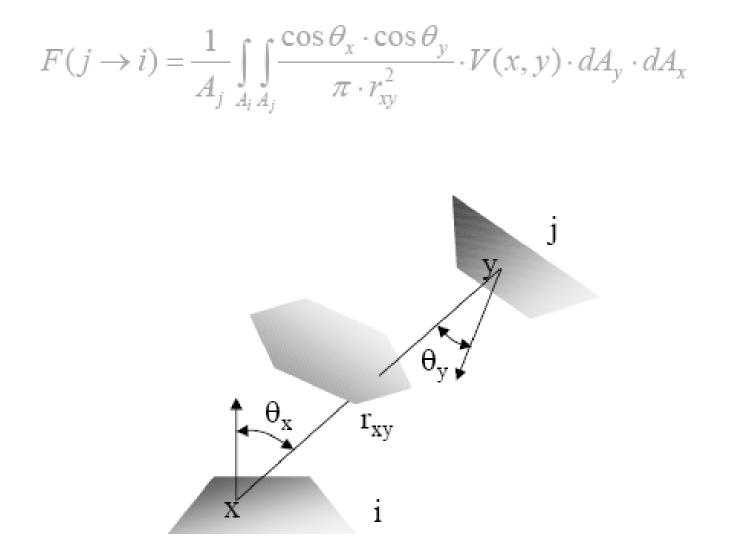




Theatre Scene



Compute Form Factors



Radiosity Equation

• Radiosity for each polygon *i*

$$B_i = B_{e,i} + \rho_i \sum_j B_j F(i \to j)$$

Linear system

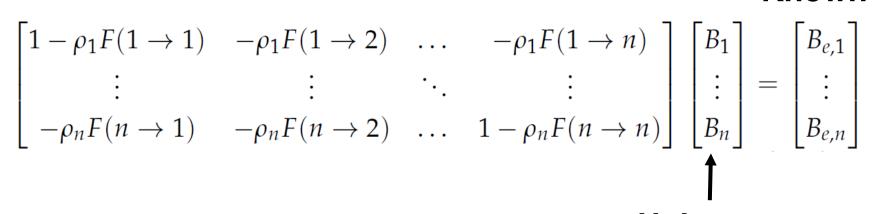
- B_i : radiosity of patch i (unknown)
- B_{e,i} : emission of patch i (known)
- ρ₁ : reflectivity of patch i (known)
- $F(i \rightarrow j)$: form-factor (coefficients of matrix)



Linear System of Radiosity

Known

Known



Unknown



How to Solve Linear System

- Matrix inversion
 - Takes O(n³)
- Gather methods
 - Jacobi iteration
 - Gauss-Seidel
- Shooting
 - Southwell iteration



Iterative Approaches

Jacobi iteration

- Start with initial guess for energy distribution (light sources)
- Update radiosity of all patches based on the previous guess

$$B_i = B_{e,i} + \rho_i \sum_j B_j F(i \to j)$$

$$I = B_{e,i} + \rho_i \sum_j B_j F(i \to j)$$

$$I = 0$$
Old values

- Repeat until converged
- Guass-Seidel iteration

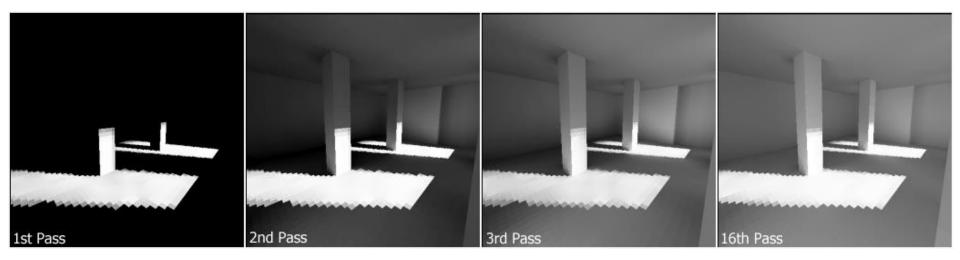
N

• New values used immediately



Progress of Update Steps

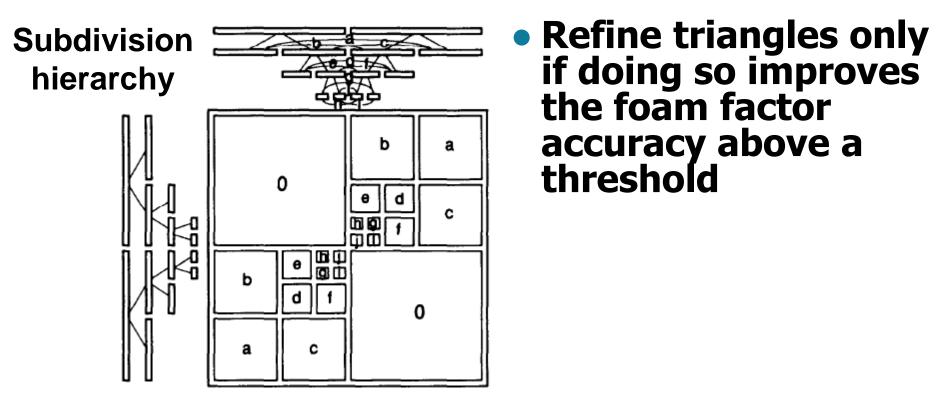
Update step supports the light bounce





Multi-Resolution Approach

• A Rapid Hierarchical Radiosity Algorithm, Hanrahan, et al, SIGGRAPH 1991



Block diagram of the form factor matrix



Hybrid and Multipass Methods

Ray tracing

- Good for specular and refractive indirect illumination
- View-dependent

Radiosity

- Good for diffuse
- Allows interactive rendering
- Does not scale well for massive models

Hybrid methods

• Combine both of them in a way

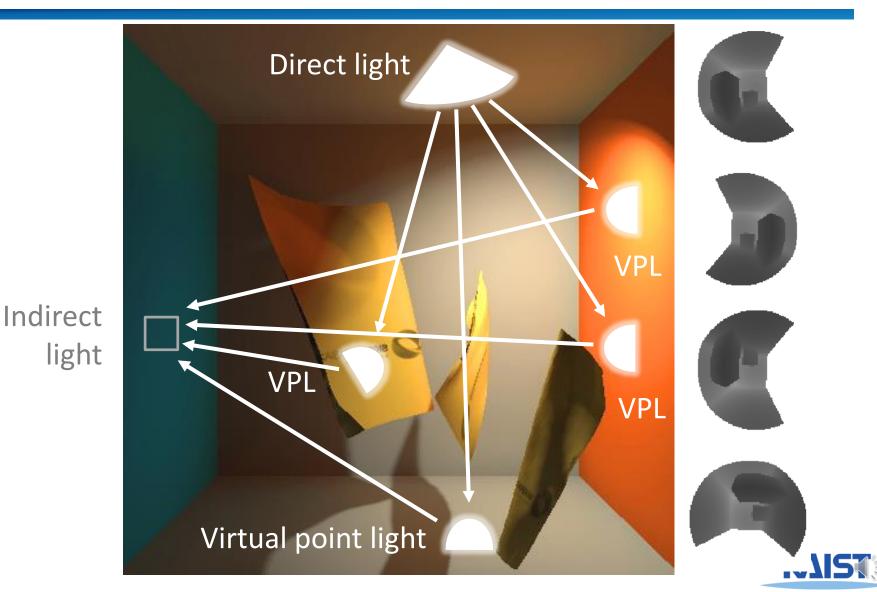


Instant Radiosity

- Use the concept of radiosity
- Map its functions to those of classic rendering pipeline
 - Utilize fast GPU
- Additional concepts
 - Virtual point lights
 - Shadow maps



Instant Radiosity

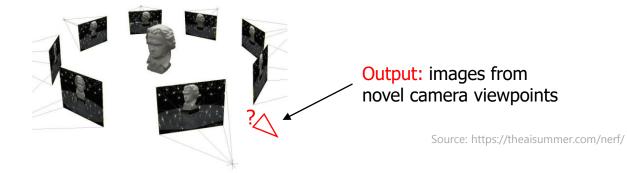


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NeRF: Neural Radiance Fields ECCV 2020 Oral - Best Paper Honorable Mention

The goal of NeRF is to synthesize photorealistic images from novel camera viewpoints.

Input: images from various camera viewpoints



Examples (synthesized from novel views)





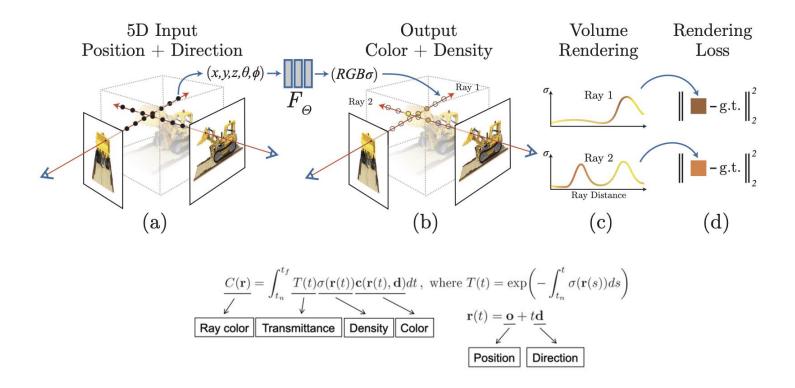


Videos: https://www.youtube.com/watch?v=JuH79E8rdKc&t=191s

https://www.matthewtancik.com/nerf



Neural Radiance Fields ECCV 2020 Oral - Best Paper Honorable Mention



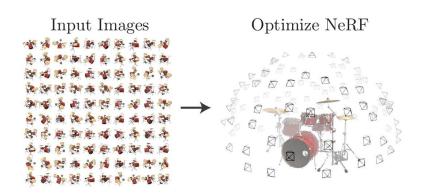


NeRF: Representing Scenes as Neural Radiance Fields for View Synthesis, ECCV 2020

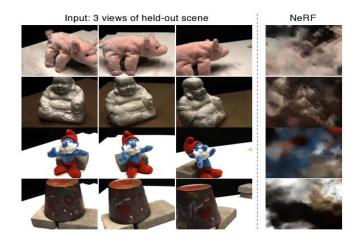
Cons of NeRF

Requires Dense camera viewpoints

Since NeRF is under-constrained it produces blurred or distorted results with sparse-view inputs. => Learning accurate 3D representation of an object requires dense views.



Dense camera viewpoints are required (e.g., 50+ source images)



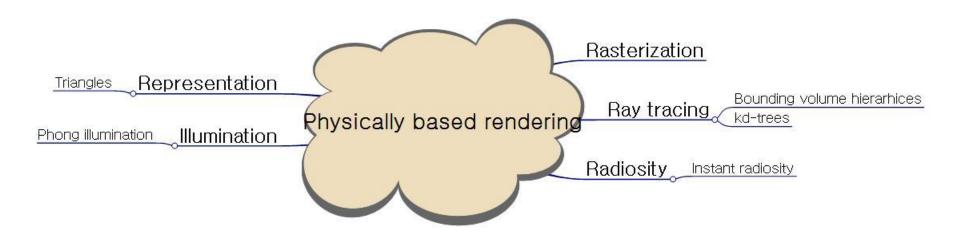


pixelNeRF: Neural Radiance Fields from One or Few Images, CVPR'21

Class Objectives were:

Understand radiosity

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Homework

- Go over the next lecture slides before the class
- Watch 2 paper videos and submit your summaries every Mon. class
 - Just one paragraph for each summary

Example:

Title: XXX XXXX XXXX

Abstract: this video is about accelerating the performance of ray tracing. To achieve its goal, they design a new technique for reordering rays, since by doing so, they can improve the ray coherence and thus improve the overall performance.



Any Questions?

- Submit four times in Sep./Oct.
- Come up with one question on what we have discussed in the class and submit at the end of the class
 - 1 for typical questions
 - 2 for questions that have some thoughts or surprise me



Next Time

Radiometry and rendering equation

