CS380: Computer Graphics Ray Tracing

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Course URL: http://sgvr.kaist.ac.kr/~sungeui/CG/



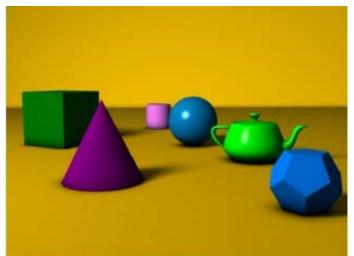
Class Objectives

- Understand overall algorithm of recursive ray tracing
 - Ray generations
 - Intersection tests
- Related chapter
 - Part II, Ch. 10: Ray Tracing



Various Visibility Algorithm

- Z-buffer
- Ray casting, etc.



A simple three dimensional scene



Z-buffer representation



Ray Casting

 For each pixel, find closest object along the ray and shade pixel accordingly

Advantages

- Conceptually simple
- Can be extended to handle global illumination effects

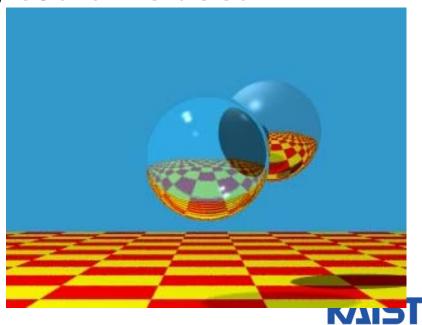
Disadvantages

- Renderer must have access to entire retained model
- Hard to map to special-purpose hardware
- Less efficient than rasterization in terms of utilizing spatial coherence



Recursive Ray Casting

- Ray casting generally dismissed early on because of aforementioned problems
- Gained popularity in when Turner Whitted (1980) showed this image
 - Show recursive ray casting could be used for global illumination effects



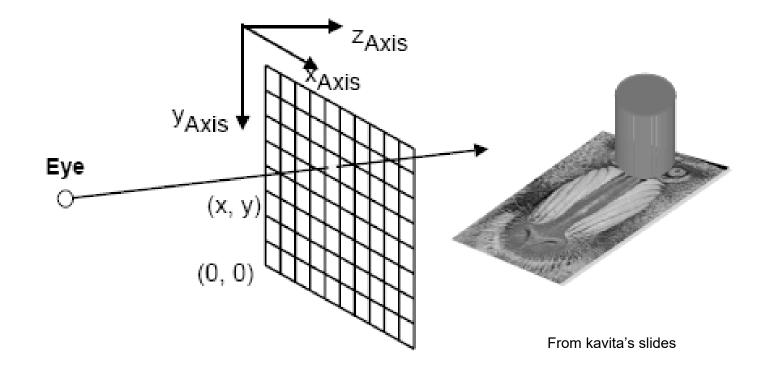
Ray Casting and Ray Tracing

- Trace rays from eye into scene
 - Backward ray tracing
- Ray casting used to compute visibility at the eye
- Perform (recursive) ray tracing for arbitrary rays needed for shading
 - Reflections
 - Refraction and transparency
 - Shadows



Basic Algorithms of Ray Tracing

 Rays are cast from the eye point through each pixel in the image

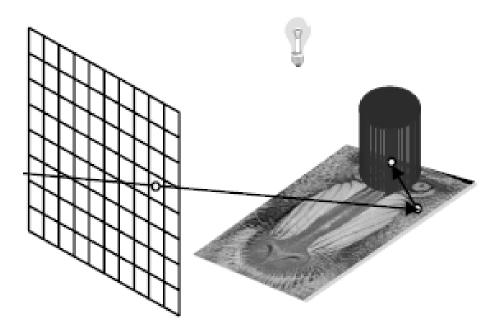


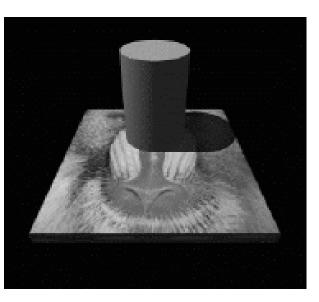


Shadows

Cast ray from the intersection point to each light source

• Shadow rays



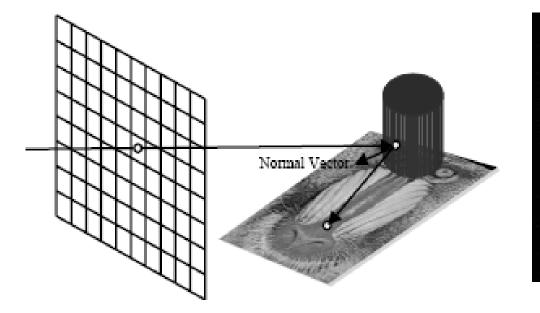


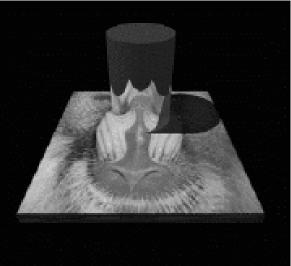
From kavita's slides



Reflections

If object specular, cast secondary reflected rays



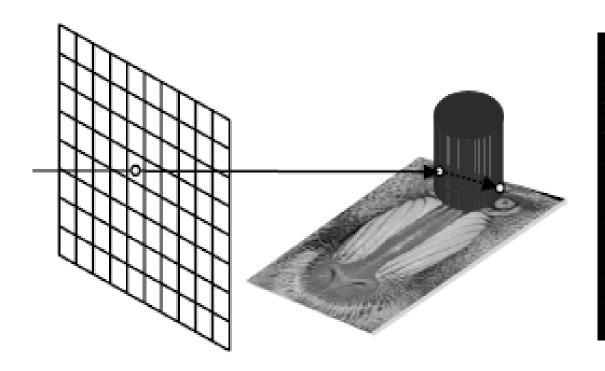


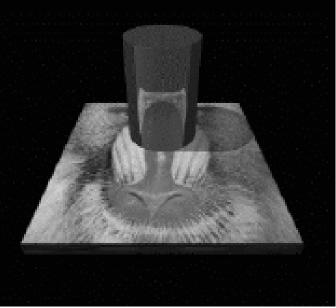
From kavita's slides



Refractions

If object tranparent, cast secondary refracted rays





From kavita's slides

Generate rays for supporting effects



An Improved Illumination Model [Whitted 80]

- Phong model $I_{r} = \sum_{j=1}^{numLights} (k_{a}^{j}I_{a}^{j} + k_{d}^{j}I_{d}^{j}(\widehat{N} \cdot \widehat{L}_{j}) + k_{s}^{j}I_{s}^{j}(\widehat{V} \cdot \widehat{R})^{n_{s}})$ • Whitted model $num_{Visible_{Lights}} I_{r} = \sum_{j=1}^{num_{Visible_{Lights}}} (k_{a}^{j}I_{a}^{j} + k_{d}^{j}I_{d}^{j}(\widehat{N} \cdot \widehat{L}_{j})) + k_{s}S + k_{t}T$
 - S and T are intensity of light from reflection and transmission rays
 - *K_s*, *K_t* are specular and transmission coefficient



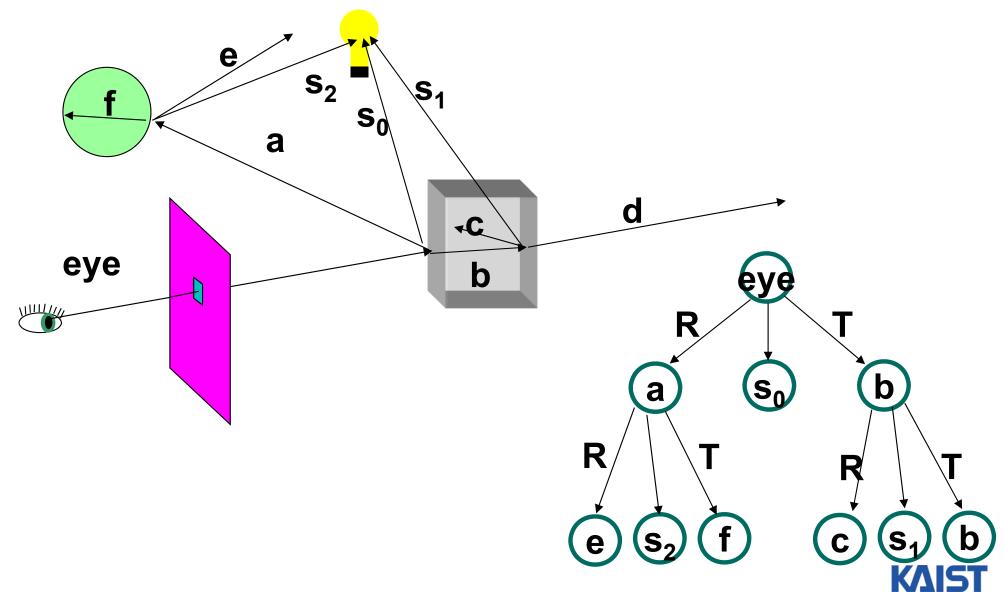
An Improved Illumination Model [Whitted 80]

numLights $I_{r} = \sum_{i=1}^{r} (k_{a}^{j}I_{a}^{j} + k_{d}^{j}I_{d}^{j}(\widehat{N} \bullet \widehat{L}_{j})) + k_{s}S + k_{t}T$ $\overline{N} + \overline{V}'$ R. **Computing reflection and** REFLECTING transmitted/refracted rays is SURFACE based on Snell's law —Ñ P



 $k_f(\bar{N}+\overline{V}')$

Ray Tree



Overall Algorithm of Ray Tracing

• Per each pixel, compute a ray, R

Def function RayTracing (R)

- Compute an intersection against objects
- If no hit,
 - Return the background color
- Otherwise,
 - Compute shading, c
 - General secondary ray, R', if necessary
 - Perform c' = RayTracing (R')
 - Return c+c'



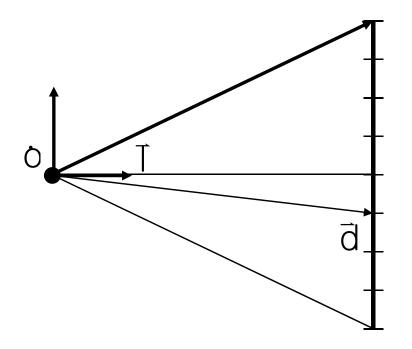
Ray Representation

- We need to compute the first surface hit along a ray
 - Represent ray with origin and direction
 - Compute intersections of objects with ray
 - Return the closest object

$$\dot{p}(t) = \dot{o} + t \vec{d}$$
 $\dot{\phi}$



Generating Primary Rays





Generating Secondary Rays

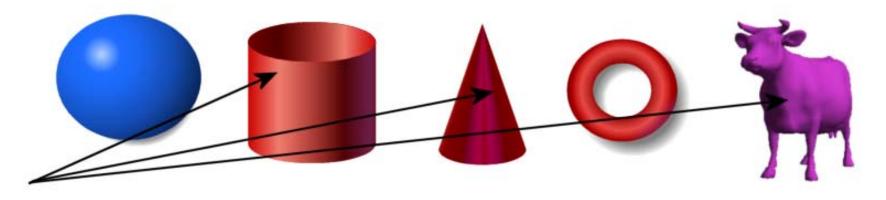
• The origin is the intersection point p₀

- Direction depends on the type of ray
 - Shadow rays use direction to the light source
 - Reflection rays use incoming direction and normal to compute reflection direction
 - Transparency/refraction use snell's law



Intersection Tests

 Go through all of the objects in the scene to determine the one closest to the origin of the ray (the eye)



Strategy

• Solve of the intersection of the ray with a mathematical description of the object



Simple Strategy

Parametric ray equation

 Gives all points along the ray as a function of the parameter

$\dot{p}(t) = \dot{o} + t \vec{d}$

- Implicit surface equation
 - Describes all points on the surface as the zero set of a function

f(p) = 0

• Substitute ray equation into surface function and solve for t $f(0+t\bar{d}) = 0$



Ray-Plane Intersection

- Implicit equation of a plane: $n \cdot p d = 0$
- Substitute ray equation:
 - $\mathbf{n} \cdot (\mathbf{o} + \mathbf{t} \, \mathbf{\vec{d}}) \mathbf{d} = \mathbf{0}$
- Solve for t:
- $t(n \cdot \vec{d}) = d n \cdot \vec{o}$ $t = \frac{d n \cdot \vec{o}}{n \cdot \vec{d}}$



Class Objectives were:

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Next Time

Acceleration structures and extensions of ray tracing



Homework

- Go over the next lecture slides before the class
- Submit questions two times during the whole semester

