# CS380: Computer Graphics Clipping and Culling 

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Course URL:
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## Class Objectives

- Understand clipping and culling
- Understand view-frustum, back-face culling, and hierarchical culling methods
- Know various possibilities to perform culling and clipping in the rendering pipeline


## Culling and Clipping

- Culling
- Throws away entire objects and primitives that cannot possibly be visible
- An important rendering optimization (esp. for large models)
- Clipping
- "Clips off" the visible portion of a primitive
- Simplifies rasterization
- Also, used to create "cut-away" views of a model


## Culling Example



Power plant model
( 12 million triangles)

## Culling Example



Full model
12 Mtris


View frustum culling Occulsion culling 10 Mtris


1 Mtris

## Lines and Planes

- I mplicit equation for line (plane):

$$
\begin{aligned}
& n_{x} x+n_{y} y-d=0 \\
& {\left[\begin{array}{lll}
n_{x} & n_{y} & -d
\end{array}\right]\left[\begin{array}{l}
x \\
y \\
1
\end{array}\right]=0 \Rightarrow T \cdot p=0}
\end{aligned}
$$



- If n is normalized then d gives the distance of the line (plane) from the origin along $n$


## Lines and Planes

- Lines (planes) partition 2D (3D) space:
- Positive and negative half-spaces
- The intersection of negative halfspaces defines a convex region



## Testing Objects for Containment



Outside


Straddling


Inside

## Conservative Testing



Outside T. $c>r$


Indeterminate $-r<T \cdot c<r$


Inside
T. $\mathrm{c}<-\mathrm{r}$

- Use cheap, conservative bounds for trivial cases
- Can use more accurate, more expensive tests for ambiguous cases if needed


## Hierarchical Culling

- Bounding volume hierarchies accelerate culling by rejecting/ accepting entire sub-trees at a time
- Bounding volume hierarchies (BVHs)
- Object partitioning hierarchies
- Uses axis-aligned bounding boxes


ABVH

## Hierarchical Culling

- Simple algorithm:
while( node is indeterminate ) recurse on children



## View Frustum Culling

- Test objects against planes defining view frustum
- How do you compute them?

- Other planes can be computed similarly


## Back-Face Culling

- Special case of occlusion - convex selfocclusion
- For closed objects (has well-defined inside and outside) some parts of the surface must be blocked by other parts of the surface
- Specifically, the backside of the object is not visible



## Face Plane Test

- Compute the plane for the face:

$$
\begin{aligned}
& \mathrm{n}=\left(\mathrm{v}_{1}-\mathrm{v}_{0}\right) \times\left(\mathrm{v}_{2}-\mathrm{v}_{0}\right) \\
& \mathrm{d}=\mathrm{n} \cdot \mathrm{v}_{0}
\end{aligned}
$$



- Cull if eye point in the negative half-space



## Back-Face Culling in OpenGL

- Can cull front faces or back faces
- Back-face culling can sometimes double performance
if (cull):
glFrontFace(GL_CCW) \# define winding order
glEnable(GL_CULL_FACE) \# enable Culling
glCullFace(GL_BACK)
\# which faces to cull
else:
glDisable(GL_CULL_FACE)

You can also do front-face culling!


## Clipping a Line Segment against a Line

- First check endpoints against the plane
- If they are on the same side, no clipping is needed
- Interpolate to get new point

$$
\begin{gathered}
p^{\prime}=p_{0}+t\left(p_{1}-p_{0}\right) \quad T \cdot p^{\prime}=0 \\
T \cdot\left(p_{0}+t\left(p_{1}-p_{0}\right)\right)=0 \\
t=\frac{-\left(T \cdot p_{0}\right)}{T \cdot\left(p_{1}-p_{0}\right)}
\end{gathered}
$$



- Vertex attributes interpolated the same way


## Clipping a Polygon against a Line

- Traverse edges
- Keep edges that are entirely inside
- Create new point when we exit
- Throw away edges entirely outside
- Create new point and new edge when we enter



## Clipping against a Convex Region

- Sutherland-Hodgman
- J ust clip against one edge at a time



## Outcodes

- The Cohen-Sutherland clipping algorithm uses outcodes to quickly determine the visibility of a 0010 primitive
- An outcode is created for each vertex

- It is a bit vector with a bit set for each plane the vertex is outside of
- Works for any convex region


## Outcode for Lines

(outcode1 OR outcode2) == 0 line segment is inside
(outcode1 AND outcode2) != 0 line segment is totally outside
(outcode1 AND outcode2) == 0
line segment potentially crosses clip region at planes indicated by set bits in
 (outcode1 XOR outcode2)

- False positive
- Some line segments that are classified as potentially crossing the clip region actually don't


## Outcodes for Triangles

Combine outcodes from vertices
(outcode1 OR outcode2 OR outcode3) == 0 triangle is inside
(outcode1 AND outcode2 AND outcode3) != 0
triangle is outside
(outcode1 AND outcode2 AND outcode3) == 0
triangle potentially crosses clip region

## Clipping in the Pipeline



Clip space

## View Frustum Clipping

- Points in projective space need to be clipped before projection
- Primitives that straddle the $z=0$ plane "flip" around infinity when projected


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## Clipping in the Clip Space

- NDC simplify view frustum clipping
- Clip after applying projection matrix, but before the divide by w
- clip coordinates


$$
\begin{aligned}
\mathrm{T}_{x+} & =\left[\begin{array}{lll}
1 & -1 & 0
\end{array}\right] \\
v_{i} & =\left[\begin{array}{lll}
x_{1} & w_{1} & I^{\top}
\end{array}\right. \\
\mathrm{t} & =\frac{\mathrm{w}_{0}-x_{0}}{\left(\mathrm{w}_{0}-x_{0}\right)-\left(\mathrm{w}_{1}-x_{1}\right)}
\end{aligned}
$$

- Easy in/ out test and interpolation


# Culling and Clipping in the Rendering Pipeline 



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## Reading Assignment

- Read the chapter "Raster Algorithms"


## Next Time

- Triangulating a polygon
- Rasterizing triangles
- Interpolating parameters

